

Lecture 7: 4 February, 2025

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Data Mining and Machine Learning
January–April 2025

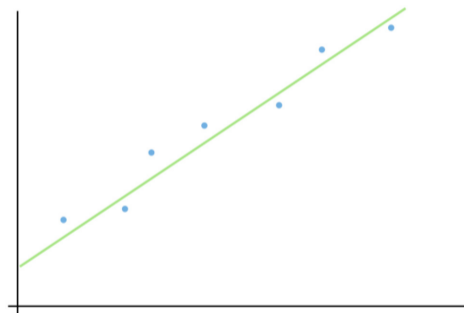
Finding the best fit line

- Training input is $\{(x_1, y_1), (x_2, y_2), \dots, (x_n, y_n)\}$
 - Each input x_i is a vector (x_i^1, \dots, x_i^k)
 - Add $x_i^0 = 1$ by convention
 - y_i is actual output
- How far away is our prediction $h_\theta(x_i)$ from the true answer y_i ?

- Define a cost (loss) function

$$J(\theta) = \frac{1}{2} \sum_{i=1}^n (h_\theta(x_i) - y_i)^2$$

- Essentially, the sum squared error (SSE)
- Divide by n , mean squared error (MSE)



Minimizing SSE

- Write x_i as row vector $[1 \ x_i^1 \ \dots \ x_i^k]$

- $$X = \begin{bmatrix} 1 & x_1^1 & \dots & x_1^k \\ 1 & x_2^1 & \dots & x_2^k \\ & & \dots & \\ 1 & x_i^1 & \dots & x_i^k \\ & & \dots & \\ 1 & x_n^1 & \dots & x_n^k \end{bmatrix}, y = \begin{bmatrix} y_1 \\ y_2 \\ \dots \\ y_i \\ \dots \\ y_n \end{bmatrix}$$

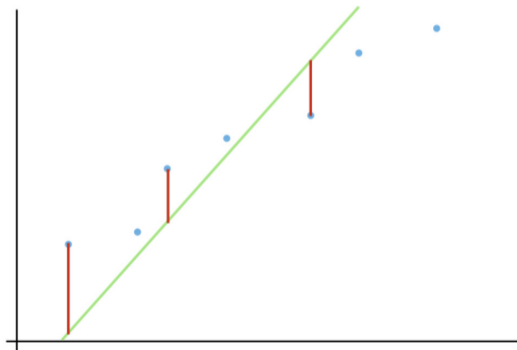
- Write θ as column vector, $\theta^T = [\theta_0 \ \theta_1 \ \dots \ \theta_k]$

- $$J(\theta) = \frac{1}{2} \sum_{i=1}^n (h_{\theta}(x_i) - y_i)^2 = \frac{1}{2} (X\theta - y)^T (X\theta - y)$$

- Minimize $J(\theta)$ — set $\nabla_{\theta} J(\theta) = 0$

Minimizing SSE iteratively

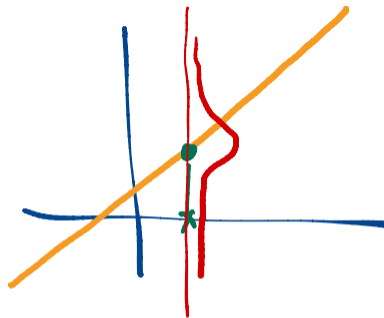
- Normal equation $\theta = (X^T X)^{-1} X^T y$ is a closed form solution
- Computational challenges
 - Matrix inversion $(X^T X)^{-1}$ is expensive, also need invertibility
- Iterative approach, make an initial guess
- Adjust each parameter against gradient
 - $\theta_i = \theta_i - \alpha \frac{\partial}{\partial \theta_i} J(\theta)$
- Stop when we converge
- Gradient descent



Regression and SSE loss

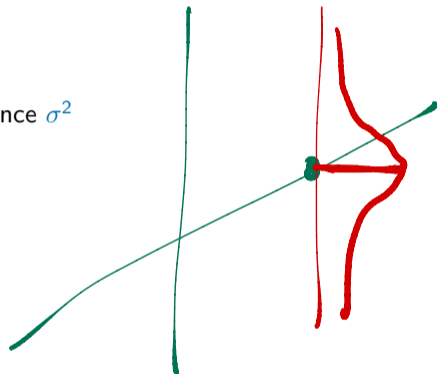
- Training input is $\{(x_1, y_1), (x_2, y_2), \dots, (x_n, y_n)\}$
 - Outputs are noisy samples from a linear function
 - $y_i = \theta^T x_i + \epsilon$

↓
"Actual line"



Regression and SSE loss

- Training input is $\{(x_1, y_1), (x_2, y_2), \dots, (x_n, y_n)\}$
 - Outputs are noisy samples from a linear function
 - $y_i = \theta^T x_i + \epsilon$
 - $\epsilon \sim \mathcal{N}(0, \sigma^2)$: Gaussian noise, mean 0, fixed variance σ^2
 - $y_i \sim \mathcal{N}(\mu_i, \sigma^2)$, $\mu_i = \theta^T x_i$
 - μ_i is underlined in green
 - σ^2 is underlined in red
 - A green arrow points to μ_i
 - Two red lines are drawn under σ^2



Regression and SSE loss

- Training input is $\{(x_1, y_1), (x_2, y_2), \dots, (x_n, y_n)\}$
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- Model gives us an estimate for θ , so regression learns μ_i for each x_i

Regression and SSE loss

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- How good is our estimate?

Regression and SSE loss

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- Model gives us an estimate for θ , so regression learns μ_i for each x_i
- How good is our estimate?
- **Likelihood** — probability of current observation given θ

$$\mathcal{L}(\theta) = \prod_{i=1}^n P(y_i | x_i; \theta)$$

N tosses, observe H heads

$$P_H = \frac{H}{N} \longrightarrow \frac{\text{Prob}(\text{observation})}{\text{LIKELIHOOD}}$$

Among all poss. P_H , $\frac{H}{N}$ maximizes the probability

Likelihood

- How good is our estimate?

Likelihood

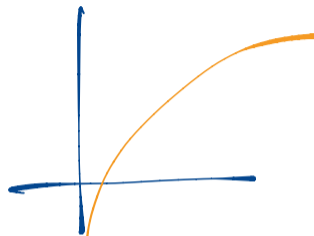
- How good is our estimate?
- Want **Maximum Likelihood Estimator (MLE)**
 - Find θ that maximizes $\mathcal{L}(\theta) = \prod_{i=1}^n P(y_i | x_i; \theta)$

Likelihood

- How good is our estimate?
- Want **Maximum Likelihood Estimator (MLE)**
 - Find θ that maximizes $\mathcal{L}(\theta) = \prod_{i=1}^n P(y_i | x_i; \theta)$
- Equivalently, maximize **log likelihood**

$$\ell(\theta) = \log \left(\prod_{i=1}^n P(y_i | x_i; \theta) \right) = \sum_{i=1}^n \log(P(y_i | x_i; \theta))$$

- Easier to work with summation than product



Log likelihood and SSE loss

■ $y_i = \mathcal{N}(\mu_i, \sigma^2)$, so $P(y_i | x_i; \theta) = \frac{1}{\sqrt{2\pi\sigma^2}} e^{-\frac{(y_i - \mu_i)^2}{2\sigma^2}}$ x_i, θ

\downarrow
 x_i, θ

Log likelihood and SSE loss

- $y_i = \mathcal{N}(\mu_i, \sigma^2)$, so $P(y_i | x_i; \theta) = \frac{1}{\sqrt{2\pi\sigma^2}} e^{-\frac{(y_i - \mu_i)^2}{2\sigma^2}} = \frac{1}{\sqrt{2\pi\sigma^2}} e^{-\frac{(y_i - \theta^T x_i)^2}{2\sigma^2}}$

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- Log likelihood

$$\ell(\theta) = \sum_{i=1}^n \log \left(\frac{1}{\sqrt{2\pi\sigma^2}} e^{-\frac{(y_i - \theta^T x_i)^2}{2\sigma^2}} \right)$$

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- Log likelihood (assuming natural logarithm)

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$$\hat{\theta}_{\text{MSE}} = \arg \max_{\theta} \left[\sum_{i=1}^n (y_i - \theta^T x_i)^2 \right]$$

Log likelihood and SSE loss

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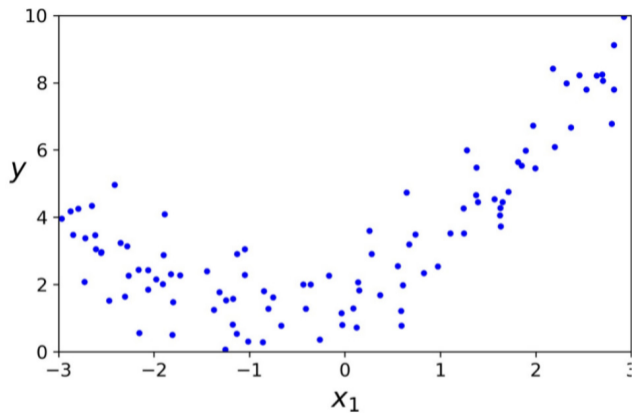
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- Assuming data points are generated by linear function and then perturbed by Gaussian noise, SSE is the “correct” loss function to maximize likelihood

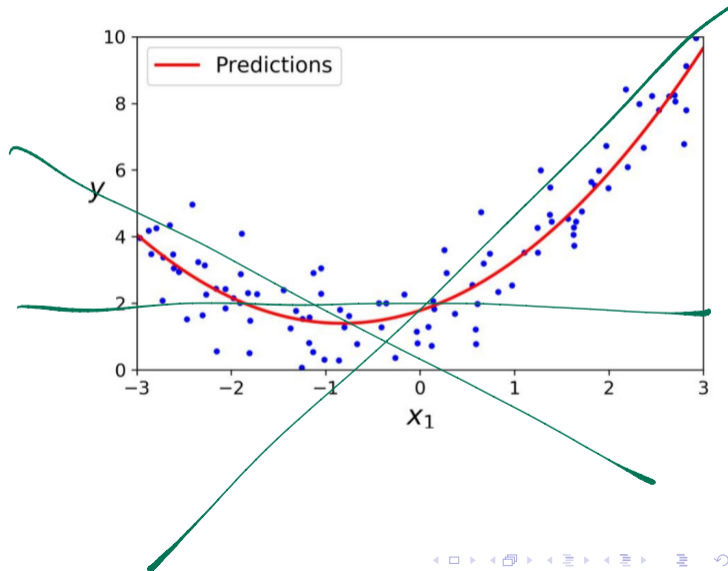
The non-linear case

- What if the relationship is not linear?



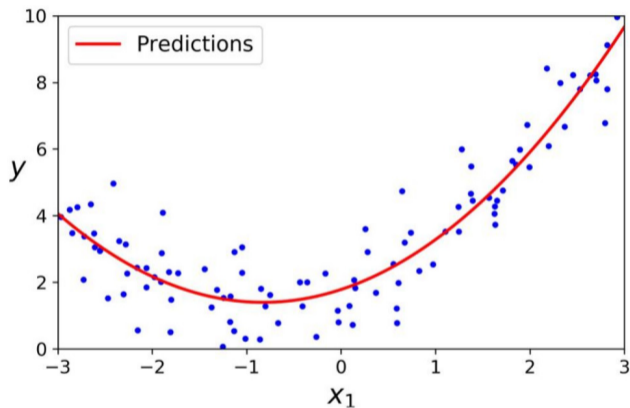
The non-linear case

- What if the relationship is not linear?
- Here the best possible explanation seems to be a quadratic



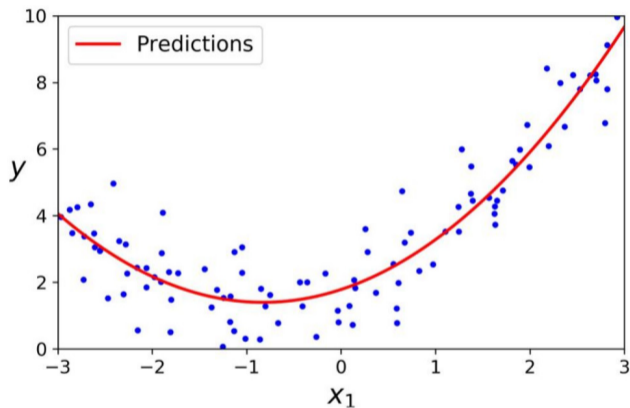
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- Non-linear : cross dependencies
- Input $x_i : (x_{i1}, x_{i2})$



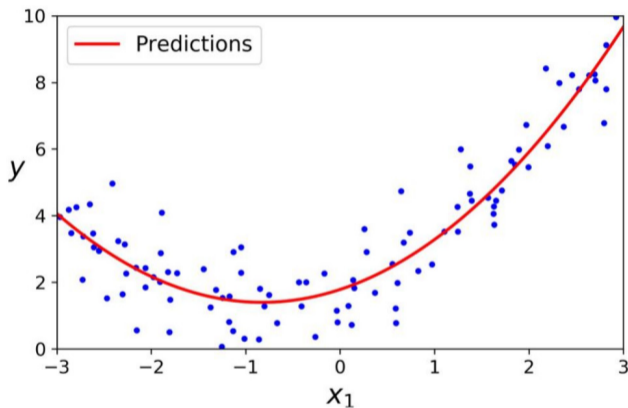
The non-linear case

- What if the relationship is not linear?
- Here the best possible explanation seems to be a quadratic
- Non-linear : cross dependencies
- Input $x_i : (x_{i1}, x_{i2})$
- Quadratic dependencies:

$$y = \theta_0 + \theta_1 x_{i1} + \theta_2 x_{i2} + \theta_{11} x_{i1}^2 + \theta_{22} x_{i2}^2 + \theta_{12} x_{i1} x_{i2}$$

LINEAR

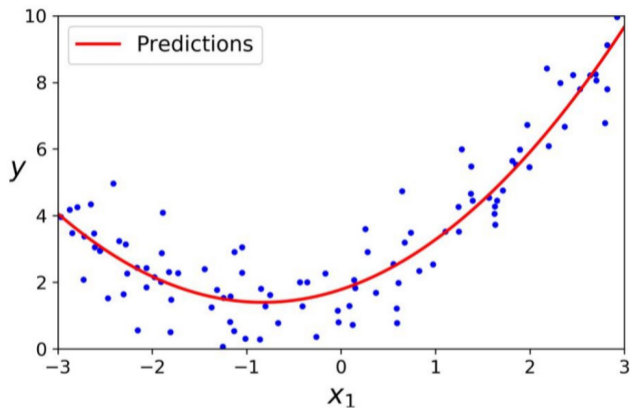
QUADRATIC



The non-linear case

- Recall how we fit a line

$$\begin{bmatrix} 1 & x_i \end{bmatrix} \begin{bmatrix} \theta_0 \\ \theta_1 \end{bmatrix}$$



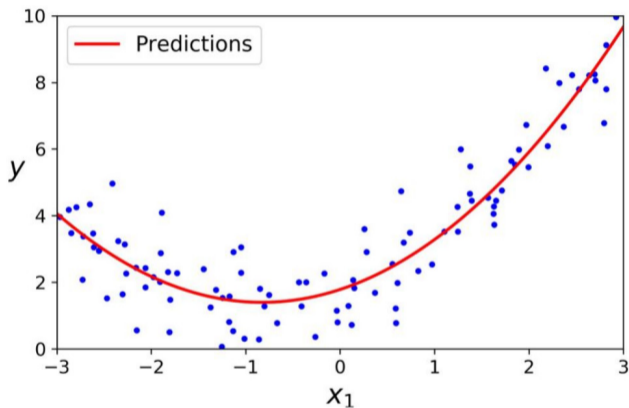
The non-linear case

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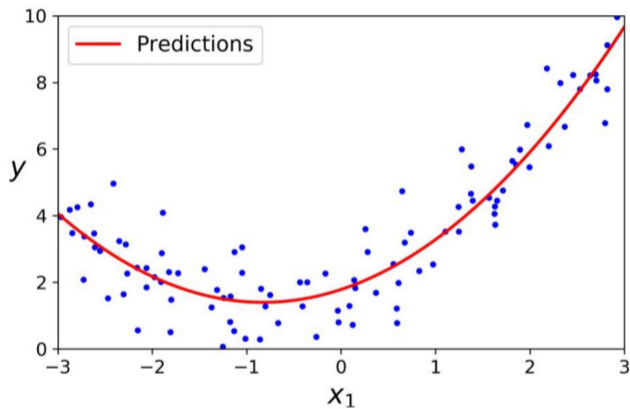
- For quadratic, add new coefficients and expand parameters

$$\begin{bmatrix} 1 & x_i & x_i^2 \end{bmatrix} \begin{bmatrix} \theta_0 \\ \theta_1 \\ \theta_2 \end{bmatrix}$$



The non-linear case

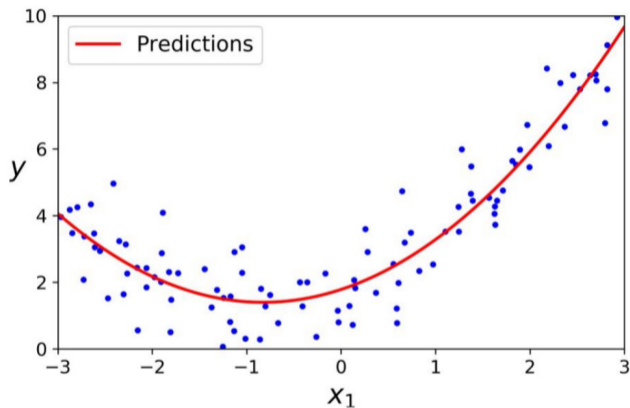
- Input (x_{i_1}, x_{i_2})



The non-linear case

- Input (x_{i_1}, x_{i_2})
- For the general quadratic case, we add new derived “features”

$$x_{i_3} = x_{i_1}^2$$
$$x_{i_4} = x_{i_2}^2$$
$$x_{i_5} = x_{i_1} x_{i_2}$$

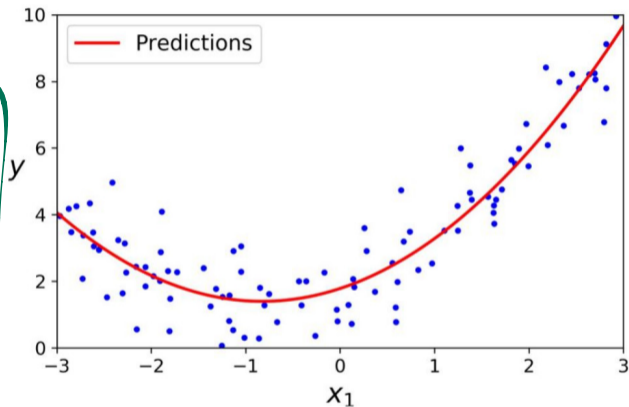


The non-linear case

- Original input matrix

$$\begin{bmatrix} 1 & x_{11} & x_{12} \\ 1 & x_{21} & x_{22} \\ \dots & \dots & \dots \\ 1 & x_{i1} & x_{i2} \\ \dots & \dots & \dots \\ 1 & x_{n1} & x_{n2} \end{bmatrix}$$

$$\begin{bmatrix} \theta_0 \\ \theta_1 \\ \theta_2 \end{bmatrix}$$



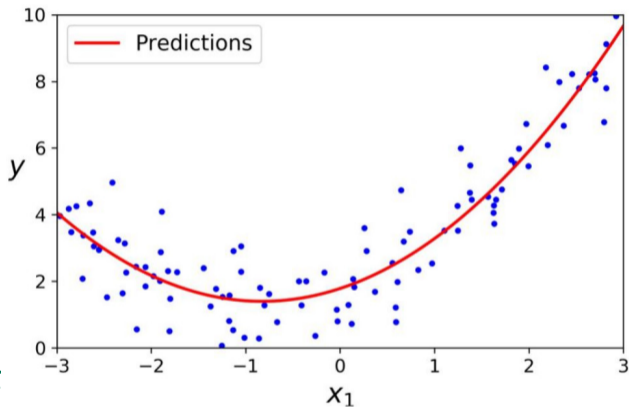
The non-linear case

- Expanded input matrix

INPUTS

$$\begin{bmatrix} 1 & x_{11} & x_{12} & x_{11}^2 & x_{12}^2 & x_{11}x_{12} \\ 1 & x_{21} & x_{22} & x_{21}^2 & x_{22}^2 & x_{21}x_{22} \\ \dots & \dots & \dots & \dots & \dots & \dots \\ 1 & x_{i1} & x_{i2} & x_{i1}^2 & x_{i2}^2 & x_{i1}x_{i2} \\ \dots & \dots & \dots & \dots & \dots & \dots \\ 1 & x_{n1} & x_{n2} & x_{n1}^2 & x_{n2}^2 & x_{n1}x_{n2} \end{bmatrix}$$

New quadratic column

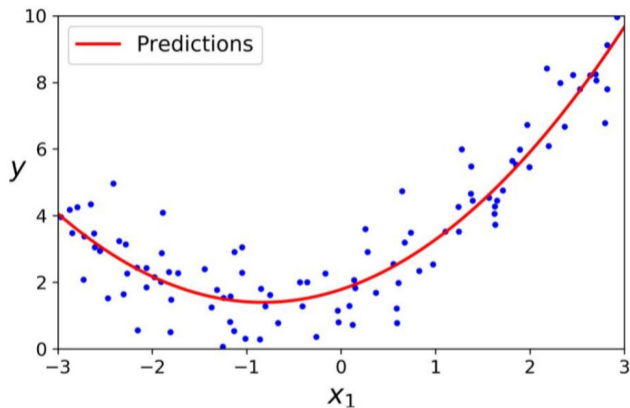


The non-linear case

- Expanded input matrix

$$\begin{bmatrix} 1 & x_{1_1} & x_{1_2} & x_{1_1}^2 & x_{1_2}^2 & x_{1_1}x_{1_2} \\ 1 & x_{2_1} & x_{2_2} & x_{2_1}^2 & x_{2_2}^2 & x_{2_1}x_{2_2} \\ \dots & \dots & \dots & \dots & \dots & \dots \\ 1 & x_{i_1} & x_{i_2} & x_{i_1}^2 & x_{i_2}^2 & x_{i_1}x_{i_2} \\ \dots & \dots & \dots & \dots & \dots & \dots \\ 1 & x_{n_1} & x_{n_2} & x_{n_1}^2 & x_{n_2}^2 & x_{n_1}x_{n_2} \end{bmatrix}$$

- New columns are computed and filled in from original inputs



Exponential parameter blow-up

■ Cubic derived features

$$x_{i_1}^3, x_{i_2}^3, x_{i_3}^3,$$

$$x_{i_1}^2 x_{i_2}, x_{i_1}^2 x_{i_3},$$

$$x_{i_2}^2 x_{i_1}, x_{i_2}^2 x_{i_3},$$

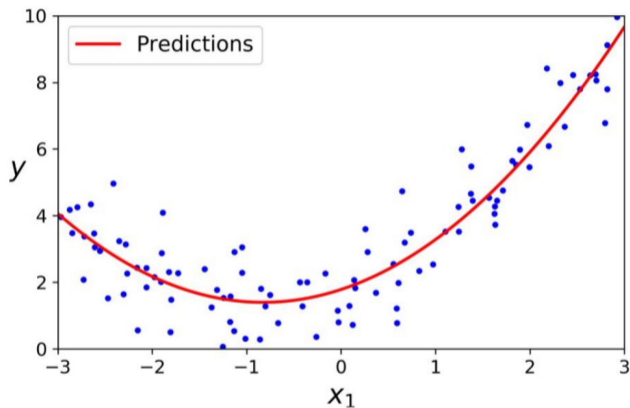
$$x_{i_3}^2 x_{i_1}, x_{i_3}^2 x_{i_2},$$

$$x_{i_1} x_{i_2} x_{i_3},$$

$$x_{i_1}^2, x_{i_2}^2, x_{i_3}^2,$$

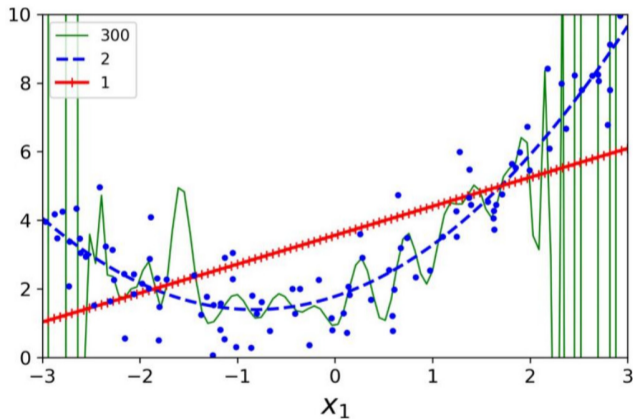
$$x_{i_1} x_{i_2}, x_{i_1} x_{i_3}, x_{i_2} x_{i_3},$$

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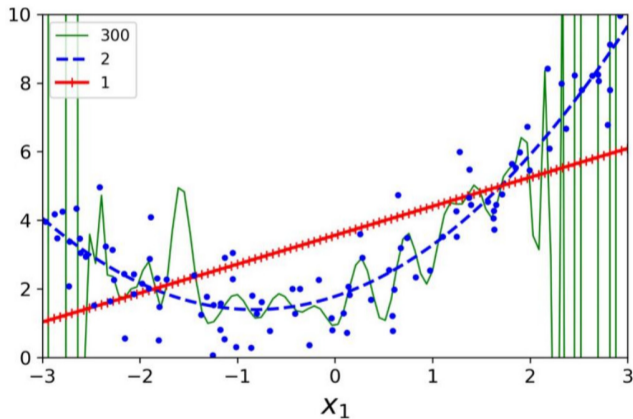
Higher degree polynomials

- How complex a polynomial should we try?



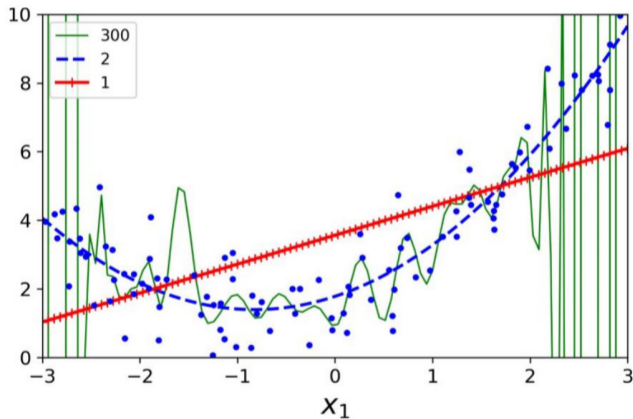
Higher degree polynomials

- How complex a polynomial should we try?
- Aim for degree that minimizes SSE



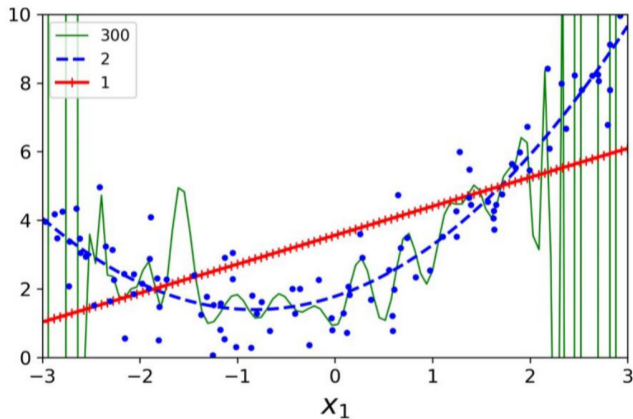
Higher degree polynomials

- How complex a polynomial should we try?
- Aim for degree that minimizes SSE
- As degree increases, features explode exponentially



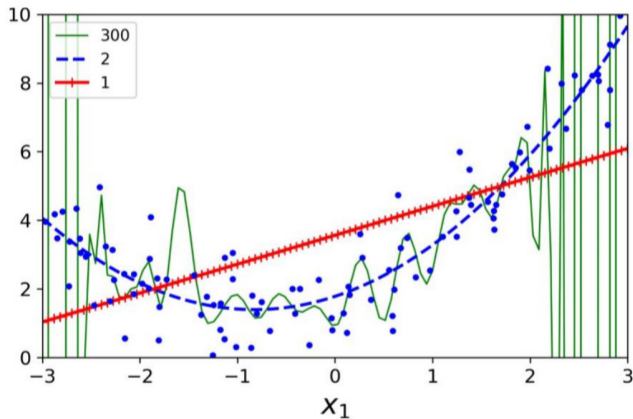
Overfitting

- Need to be careful about adding higher degree terms



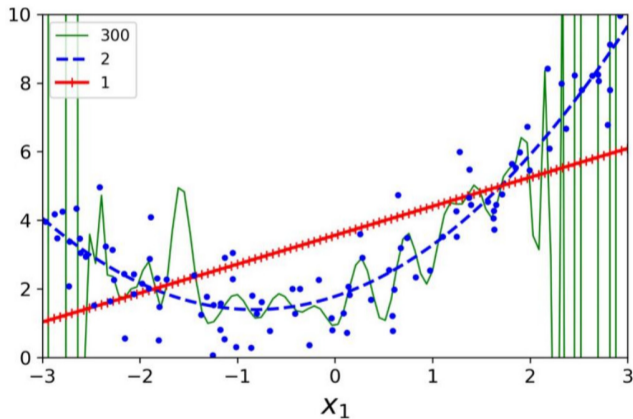
Overfitting

- Need to be careful about adding higher degree terms
- For n training points, can always fit polynomial of degree $(n - 1)$ exactly
- However, such a curve would not generalize well to new data points



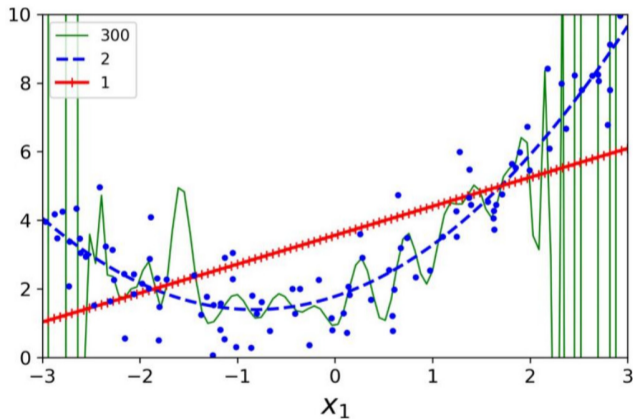
Overfitting

- Need to be careful about adding higher degree terms
- For n training points, can always fit polynomial of degree $(n - 1)$ exactly
- However, such a curve would not generalize well to new data points
- **Overfitting** — model fits training data well, performs poorly on unseen data



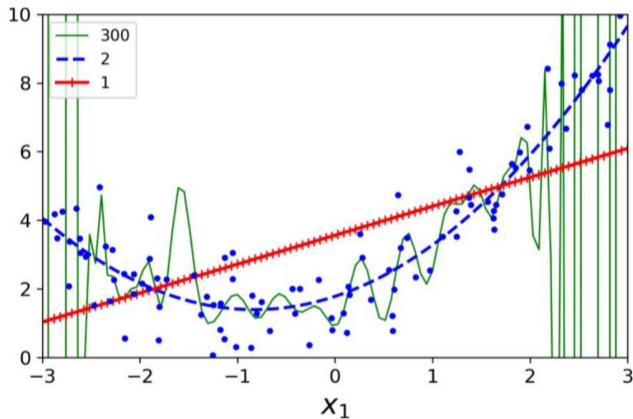
Regularization

- Need to trade off SSE against curve complexity



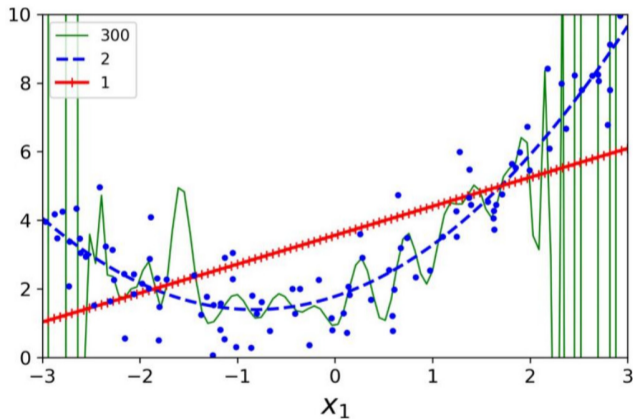
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- So far, the only cost has been SSE



Regularization

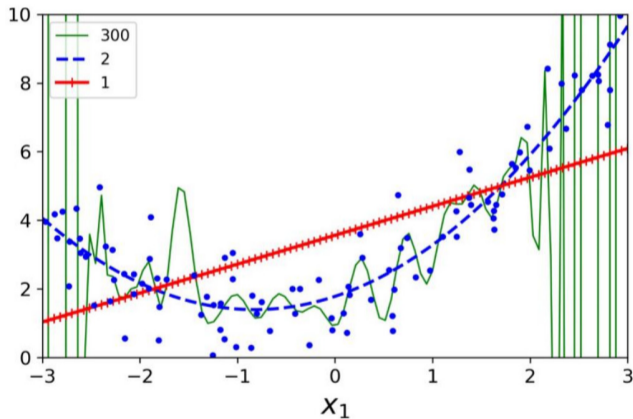
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- Add a cost related to parameters $(\theta_0, \theta_1, \dots, \theta_k)$



Regularization

- Need to trade off SSE against curve complexity
- So far, the only cost has been SSE
- Add a cost related to parameters $(\theta_0, \theta_1, \dots, \theta_k)$
- Minimize, for instance

$$\frac{1}{2} \sum_{i=1}^n (z_i - y_i)^2 + \sum_{j=1}^k \theta_j^2$$



Regularization

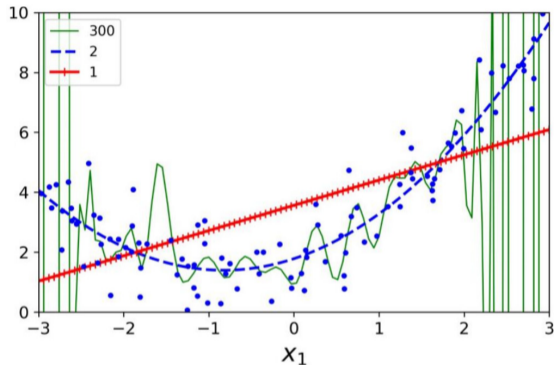
$$\frac{1}{2} \sum_{i=1}^n (z_i - y_i)^2 + \sum_{j=1}^k \theta_j^2$$

- Second term penalizes curve complexity
- Variations on regularization

- Ridge regression: $\sum_{j=1}^k \theta_j^2$

- LASSO regression: $\sum_{j=1}^k |\theta_j|$

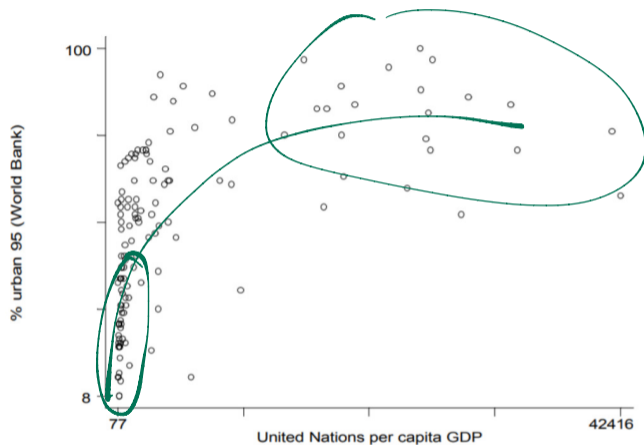
- Elastic net regression: $\sum_{j=1}^k \lambda_1 |\theta_j| + \lambda_2 \theta_j^2$



$$\lambda_1 + \lambda_2 = 1$$

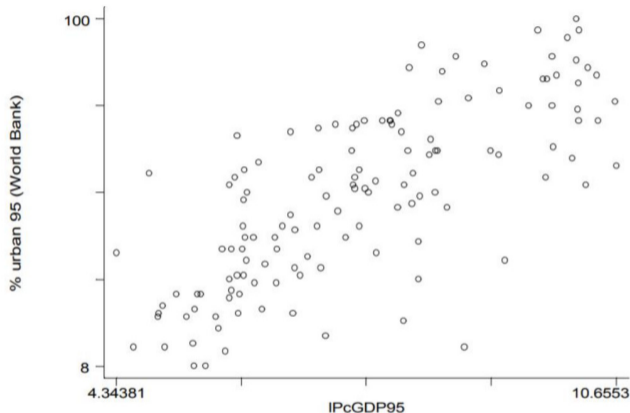
The non-polynomial case

- Percentage of urban population as a function of per capita GDP
- Not clear what polynomial would be reasonable



The non-polynomial case

- Percentage of urban population as a function of per capita GDP
- Not clear what polynomial would be reasonable
- Take log of GDP
- Regression we are computing is
 $y = \theta_0 + \theta_1 \log x_1$



The non-polynomial case

- Reverse the relationship
- Plot per capita GDP in terms of percentage of urbanization
- Now we take log of the output variable
 $\log y = \theta_0 + \theta_1 x_1$
- Log-linear transformation
- Earlier was linear-log
- Can also use log-log

