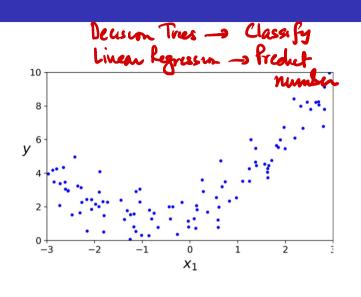
#### Lecture 8: 6 February, 2025

Madhavan Mukund https://www.cmi.ac.in/~madhavan

Data Mining and Machine Learning January–April 2025

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• Can we use decision trees for regression?



Class

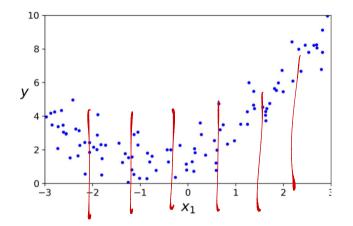
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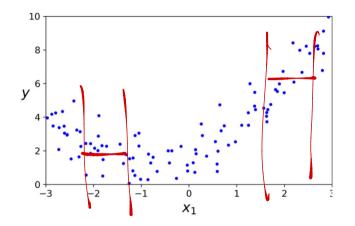
Class 1

 $v_0 \leq A \leq v_1$ 

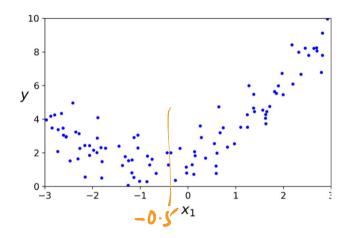
- Can we use decision trees for regression?
- Partition the input into intervals

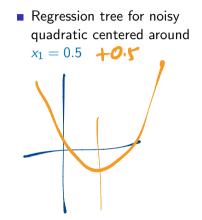


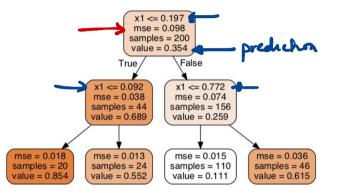
- Can we use decision trees for regression?
- Partition the input into intervals
- For each interval, predict mean value of output, instead of majority class



- Can we use decision trees for regression?
- Partition the input into intervals
- For each interval, predict mean value of output, instead of majority class
- Regression tree

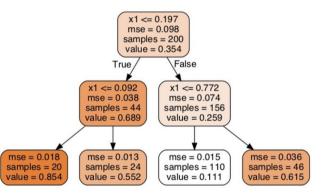




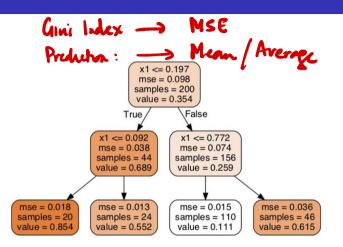


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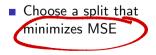
- Regression tree for noisy quadratic centered around x<sub>1</sub> = 0.5
- For each node, the output is the mean y value for the current set of points

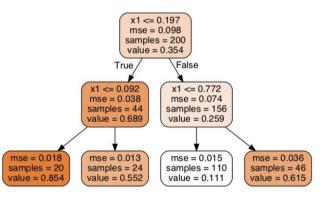


- Regression tree for noisy quadratic centered around x<sub>1</sub> = 0.5
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- Instead of impurity, use mean squared error (MSE) as cost function



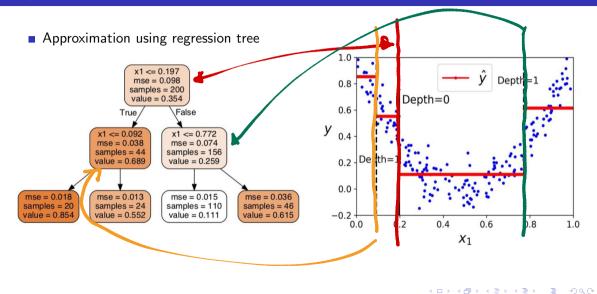
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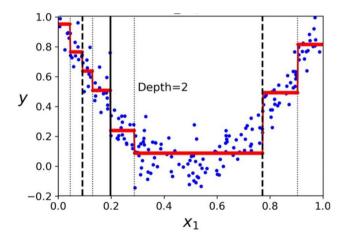


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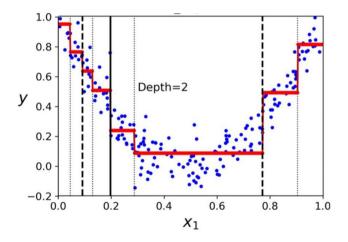
## Regression trees



 Extend the regression tree one more level to get a finer approximation

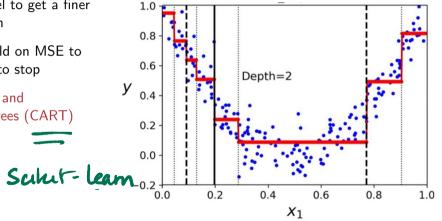


- Extend the regression tree one more level to get a finer approximation
- Set a threshold on MSE to decide when to stop

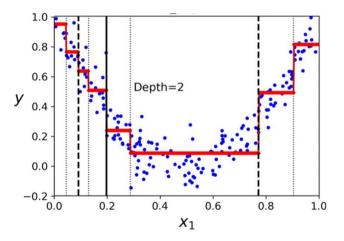


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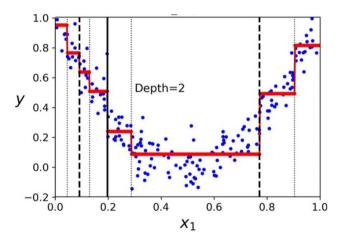
- Extend the regression tree one more level to get a finer approximation
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- Classification and Regression Trees (CART)



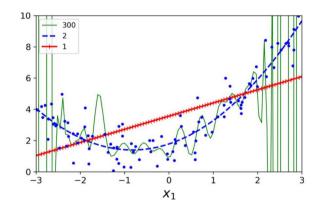
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  - Combined algorithm for both use cases



- Extend the regression tree one more level to get a finer approximation
- Set a threshold on MSE to decide when to stop
- Classification and Regression Trees (CART)
  - Combined algorithm for both use cases
- Programming libraries typically provide CART implementation



 Overfitting: model too specific to training data, does not generalize well



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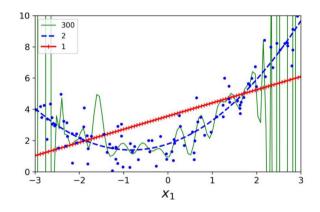
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- Regression to penalize n

to training data, does not  
generalize well  
Regression — use regularization  
to penalize model complexity  

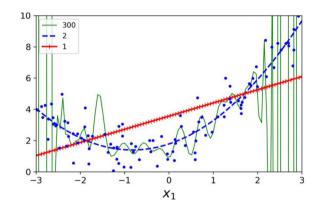
$$SSE + Model Size$$
  
 $\theta_{2} \left( \theta_{0}, \dots, \theta_{k} \right)^{2}$   
 $\theta_{2} \left( \theta_{0}, \dots, \theta_{k} \right)^{2}$   
 $\xi = \theta_{1}^{2} \left( \theta_{1}, \dots, \theta_{k} \right)^{2}$   
 $\theta_{2} \left( \theta_{1}, \dots, \theta_{k} \right)^{2}$   
 $\theta_{2} \left( \theta_{1}, \dots, \theta_{k} \right)^{2}$   
 $\theta_{1} \left( \theta_{1} \right)^{2}$ 

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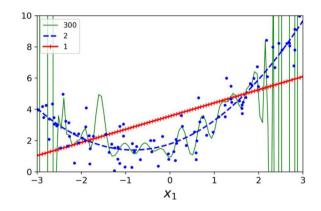
- Overfitting: model too specific to training data, does not generalize well
- Regression use regularization to penalize model complexity
- What about decision trees?



- Overfitting: model too specific to training data, does not generalize well
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- Deep, complex trees ask too many questions



- Overfitting: model too specific to training data, does not generalize well
- Regression use regularization to penalize model complexity
- What about decision trees?
- Deep, complex trees ask too many questions
- Prefer shallow, simple trees



Remove leaves to improve generalization



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- Remove leaves to improve generalization
- Top-down pruning
  - Fix a maximum depth when building the tree
  - How to decide the depth in advance?

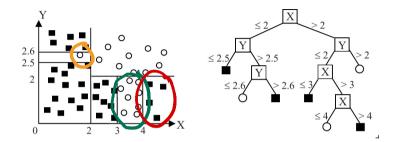
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- Remove leaves to improve generalization
- Top-down pruning
  - Fix a maximum depth when building the tree
  - How to decide the depth in advance?

#### Bottom-up pruning

- Build the full tree
- Remove a leaf if the reduced tree generalizes better
- How do we measure this?

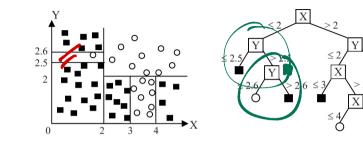
#### Overfitted tree



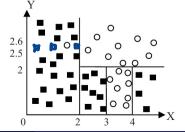
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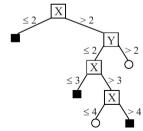
Image: A matrix

#### Overfitted tree



#### Pruned tree





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  - Estimate comes with a confidence interval  $h/h \pm \delta$
  - As *n* increases,  $\delta$  reduces: 7 heads out of 10 vs 70 out of 100 vs 700 out of 1000

Given 
$$\frac{h}{n}$$
,  $n \rightarrow fixes \sigma$ 

- Build the full tree, remove leaf if the reduced tree generalizes better
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- Impure node, majority prediction, compute confidence interval
- Pruning leaves creates a larger impure sample one level above
- Does the confidence interval decrease (improve)?

## Example: Predict party from voting pattern [Quinlan]

- Predict party affiliation of US legislators based on voting pattern
  - Read the tree from left to right

```
physician fee freeze = n:
    adoption of the budget resolution = y; demog
    adoption of the budget resolution = u: democrat (1)
    adoption of the budget resolution = n:
        education spending = n: democrat (6)
                                                hire
        education spending = v: democrat (9)
        education spending = u: republican (1)
physician fee freeze = y:
    synfuels corporation cutback = n: republican (97/3)
    synfuels corporation cutback = u: republican (4)
    synfuels corporation cutback == v:
        duty free exports = v: democrat (2)
        duty free exports = u: republicar (1)
        duty free exports == n:
            education spending = n: democrat (5/2)
            education spending = y: republican (13/2)
            education spending == u: democrat (1)
physician fee freeze = u:
    water project cost sharing = n: democrat (0)
    water project cost sharing = y: democrat (4)
    water project cost sharing = u:
        mx missile = n: republican (0)
        mx missile = y: democrat (3/1)
        mx missile = u: republican (2)
```

## Example: Predict party from voting pattern [Quinlan]

- Predict party affiliation of US legislators based on voting pattern
  - Read the tree from left to right
- After pruning, drastically simplified tree

physician fee freeze = n: democrat (168/2.6) physician fee freeze = y: republican (123/13.9) physician fee freeze = u: mx missile = n: democrat (3/1.1) mx missile = y: democrat (4/2.2) mx missile = u: republican (2/1)

# Example: Predict party from voting pattern [Quinlan]

- Predict party affiliation of US legislators based on voting pattern
  - Read the tree from left to right
- After pruning, drastically simplified tree
- Quinlan's comment on his use of sampling theory for post-pruning

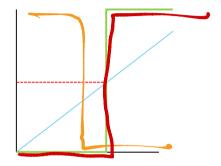
Now, this description does violence to statistical notions of sampling and confidence limits, so the reasoning should be taken with a large grain of salt. Like many heuristics with questionable underpinnings, however, the estimates it produces seem frequently to yield acceptable results.

```
physician fee freeze = n: democrat (168/2.6)
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physician fee freeze = u:
mx missile = n: democrat (3/1.1)
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```

- Regression line
- Set a threshold
- Classifier
  - Output below threshold : 0 (No)
  - Output above threshold : 1 (Yes)

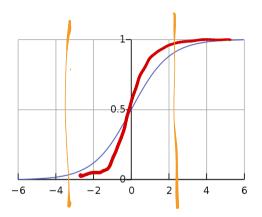
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- Regression line
- Set a threshold
- Classifier
  - Output below threshold : 0 (No)
  - Output above threshold : 1 (Yes)
- Classifier output is a step function



Sigmoid function

$$\sigma(z) = \frac{1}{1 + e^{-z}}$$



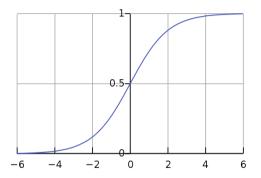
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Sigmoid function

$$\sigma(z) = \frac{1}{1 + e^{-z}}$$

Input z is output of our regression

$$\sigma(z) = \frac{1}{1 + e^{-(\frac{\theta_0 + \theta_1 x_1 + \dots + \theta_k x_k}{2})}}$$



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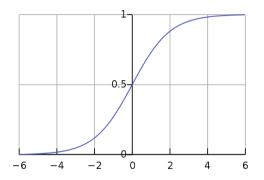
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 Adjust parameters to fix horizontal position and steepness of step

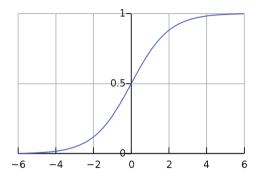


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# Logistic regression

Compute the coefficients?

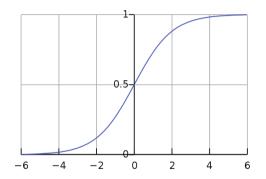
Solve by gradient descent



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# Logistic regression

- Compute the coefficients?
- Solve by gradient descent
- Need derivatives to exist
  - Hence smooth sigmoid, not step function
  - $\sigma'(z) = \sigma(z)(1 \sigma(z))$

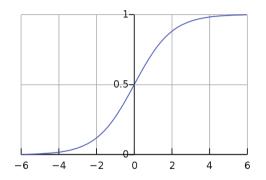


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# Logistic regression

- Compute the coefficients?
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- Need derivatives to exist
  - Hence smooth sigmoid, not step function
  - $\sigma'(z) = \sigma(z)(1 \sigma(z))$
- Need a cost function to minimize



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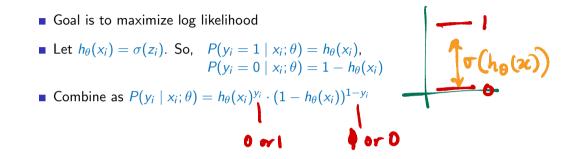
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Goal is to maximize log likelihood

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- Goal is to maximize log likelihood
- Let  $h_{\theta}(x_i) = \sigma(z_i)$ .

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Goal is to maximize log likelihood

• Let 
$$h_{\theta}(x_i) = \sigma(z_i)$$
. So,  $P(y_i = 1 \mid x_i; \theta) = h_{\theta}(x_i)$ ,  
 $P(y_i = 0 \mid x_i; \theta) = 1 - h_{\theta}(x_i)$ 

• Combine as  $P(y_i \mid x_i; \theta) = h_{\theta}(x_i)^{y_i} \cdot (1 - h_{\theta}(x_i))^{1-y_i}$ 

• Likelihood: 
$$\mathcal{L}(\theta) = \prod_{i=1}^n h_{\theta}(x_i)^{y_i} \cdot (1 - h_{\theta}(x_i))^{1-y_i}$$

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Goal is to maximize log likelihood

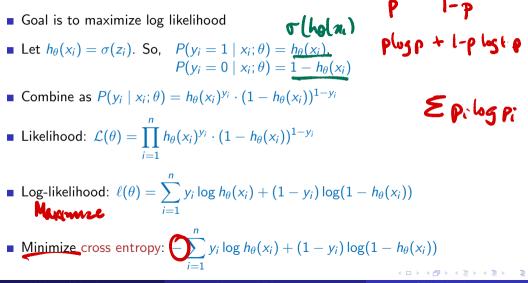
• Let  $h_{\theta}(x_i) = \sigma(z_i)$ . So,  $P(y_i = 1 \mid x_i; \theta) = h_{\theta}(x_i)$ ,  $P(y_i = 0 \mid x_i; \theta) = 1 - h_{\theta}(x_i)$ 

• Combine as  $P(y_i \mid x_i; \theta) = h_{\theta}(x_i)^{y_i} \cdot (1 - h_{\theta}(x_i))^{1-y_i}$ 

Likelihood: 
$$\mathcal{L}(\theta) = \prod_{i=1}^{n} h_{\theta}(x_i)^{y_i} \cdot (1 - h_{\theta}(x_i))^{1-y_i}$$

• Log-likelihood: 
$$\ell(\theta) = \sum_{i=1}^{n} y_i \log h_{\theta}(x_i) + (1 - y_i) \log(1 - h_{\theta}(x_i))$$

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- Suppose we take mean sum-squared error as the loss function.
- Consider two inputs  $x = (x_1, x_2)$

$$C = \frac{1}{n} \sum_{i=1}^{n} (y_i - \sigma(z_i))^2, \text{ where } z_i = \theta_0 + \theta_1 x_{i_1} + \theta_2 x_{i_2}$$

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, where  $z_i = \theta_0 + \theta_1 x_{i_1} + \theta_2 x_{i_2}$ 

• For gradient descent, we compute  $\frac{\partial C}{\partial \theta_1}$ ,  $\frac{\partial C}{\partial \theta_2}$ ,  $\frac{\partial C}{\partial \theta_0}$ 

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• For gradient descent, we compute  $\frac{\partial C}{\partial \theta_1}$ ,  $\frac{\partial C}{\partial \theta_2}$ ,  $\frac{\partial C}{\partial \theta_0}$ 

• For 
$$j = 1, 2$$
,  
 $\frac{\partial C}{\partial \theta_j} = \frac{2}{n} \sum_{i=1}^n (y_i - \sigma(z_i)) \cdot - \frac{\partial \sigma(z_i)}{\partial \theta_j}$ 

- Suppose we take mean sum-squared error as the loss function.
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$$C = \frac{1}{n} \sum_{i=1}^{n} (y_i - \sigma(z_i))^2$$
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- Suppose we take mean sum-squared error as the loss function.
- Consider two inputs  $x = (x_1, x_2)$

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• For gradient descent, we compute  $\frac{\partial C}{\partial \theta_1}$ ,  $\frac{\partial C}{\partial \theta_2}$ ,  $\frac{\partial C}{\partial \theta_0}$ 

• For 
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$$\frac{\partial C}{\partial \theta_j} = \frac{2}{n} \sum_{i=1}^n (y_i - \sigma(z_i)) \cdot -\frac{\partial \sigma(z_i)}{\partial \theta_j} = \frac{2}{n} \sum_{i=1}^n (\sigma(z_i) - y_i) \frac{\partial \sigma(z_i)}{\partial z_i} \frac{\partial z_i}{\partial \theta_j}$$

$$= \frac{2}{n} \sum_{i=1}^n (\sigma(z_i) - y_i) \sigma'(z_i) x_{i_j}$$

$$\underbrace{\mathbf{v}(z) (i - \mathbf{v}(z))}$$

- Suppose we take mean sum-squared error as the loss function.
- Consider two inputs  $x = (x_1, x_2)$

$$C = \frac{1}{n} \sum_{i=1}^{n} (y_i - \sigma(z_i))^2$$
, where  $z_i = \theta_0 + \theta_1 x_{i_1} + \theta_2 x_{i_2}$ 

• For gradient descent, we compute  $\frac{\partial C}{\partial \theta_1}$ ,  $\frac{\partial C}{\partial \theta_2}$ ,  $\frac{\partial C}{\partial \theta_0}$ 

• For 
$$j = 1, 2$$
,  

$$\frac{\partial C}{\partial \theta_j} = \frac{2}{n} \sum_{i=1}^n (y_i - \sigma(z_i)) \cdot -\frac{\partial \sigma(z_i)}{\partial \theta_j} = \frac{2}{n} \sum_{i=1}^n (\sigma(z_i) - y_i) \frac{\partial \sigma(z_i)}{\partial z_i} \frac{\partial z_i}{\partial \theta_j}$$

$$= \frac{2}{n} \sum_{i=1}^n (\sigma(z_i) - y_i) \sigma'(z_i) x_i$$

$$\frac{\partial C}{\partial \theta_0} = \frac{2}{n} \sum_{i=1}^n (\sigma(z_i) - y_i) \frac{\partial \sigma(z_i)}{\partial z_i} \frac{\partial z_i}{\partial \theta_0} = \frac{2}{n} \sum_{i=1}^n (\sigma(z_i) - y_i) \sigma'(z_i)$$
Mediate Metric

• For 
$$j = 1, 2$$
,  $\frac{\partial C}{\partial \theta_j} = \frac{2}{n} \sum_{i=1}^n (\sigma(z_i) - y_i) \sigma'(z_i) x_j^i$ , and  $\frac{\partial C}{\partial \theta_0} = \frac{2}{n} \sum_{i=1}^n (\sigma(z_i) - y_i) \sigma'(z_i)$   
• Each term in  $\frac{\partial C}{\partial \theta_1}$ ,  $\frac{\partial C}{\partial \theta_2}$ ,  $\frac{\partial C}{\partial \theta_0}$  is proportional to  $\sigma'(z_i)$ 

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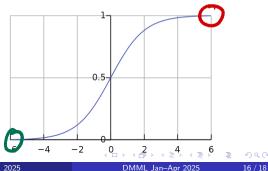
• For 
$$j = 1, 2$$
,  $\frac{\partial C}{\partial \theta_j} = \frac{2}{n} \sum_{i=1}^n (\sigma(z_i) - y_i) \sigma'(z_i) x_j^i$ , and  $\frac{\partial C}{\partial \theta_0} = \frac{2}{n} \sum_{i=1}^n (\sigma(z_i) - y_i) \sigma'(z_i)$   
• Each term in  $\frac{\partial C}{\partial \theta_1}$ ,  $\frac{\partial C}{\partial \theta_2}$ ,  $\frac{\partial C}{\partial \theta_0}$  is proportional to  $\sigma'(z_i)$ 

Ideally, gradient descent should take large steps when  $\sigma(z) - y$  is large

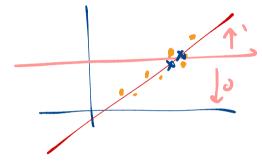
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• Each term in  $\frac{\partial C}{\partial \theta_1}$ ,  $\frac{\partial C}{\partial \theta_2}$ ,  $\frac{\partial C}{\partial \theta_0}$  is proportional to  $\sigma'(z_i)$ 

- Ideally, gradient descent should take large steps when  $\sigma(z) y$  is large
- $\sigma(z)$  is flat at both extremes
- If  $\sigma(z)$  is completely wrong,  $\sigma(z) \approx (1-y)$ , we still have  $\sigma'(z) \approx 0$
- Learning is slow even when current model is far from optimal



•  $C = -[y \ln(\sigma(z)) + (1 - y) \ln(1 - \sigma(z))]$ 



| Madhavan | Mukunc |
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•  $C = -[y \ln(\sigma(z)) + (1 - y) \ln(1 - \sigma(z))]$ 

 $\frac{\partial C}{\partial \theta_j} = \frac{\partial C}{\partial \sigma} \frac{\partial \sigma}{\partial \theta_j}$ 

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$$C = -[y \ln(\sigma(z)) + (1 - y) \ln(1 - \sigma(z))]$$

• 
$$\frac{\partial C}{\partial \theta_j} = \frac{\partial C}{\partial \sigma} \frac{\partial \sigma}{\partial \theta_j} = -\left[\frac{y}{\sigma(z)} - \frac{1-y}{1-\sigma(z)}\right] \frac{\partial \sigma}{\partial \theta_j}$$

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=  $-\left[\frac{y}{\sigma(z)} - \frac{1-y}{1-\sigma(z)}\right] \sigma'(z) x_j$ 

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 $= -\left[\frac{y}{\sigma(z)} - \frac{1-y}{1-\sigma(z)}\right] \sigma'(z)x_j$   
 $= -\left[\frac{y(1-\sigma(z)) - (1-y)\sigma(z)}{\sigma(z)(1-\sigma(z))}\right] \frac{\sigma'(z)x_j}{\sigma(z)(1-\sigma(z))}$ 

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$$\frac{\partial C}{\partial \theta_j} = -\left[\frac{y(1-\sigma(z))-(1-y)\sigma(z)}{\sigma(z)(1-\sigma(z))}\right]\sigma'(z)x_j$$

• Recall that  $\sigma'(z) = \sigma(z)(1 - \sigma(z))$ 

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Therefore, 
$$\frac{\partial C}{\partial \theta_j} = -[y(1 - \sigma(z)) - (1 - y)\sigma(z)]x_j$$
  
=  $-[y - y\sigma(z) - \sigma(z) + y\sigma(z)]x_j$ 

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 $= (\sigma(z) - y)x_j$   
• Similarly,  $\frac{\partial C}{\partial \theta_0} = (\sigma(z) - y)$ 

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• Similarly, 
$$\frac{\partial C}{\partial \theta_0} = (\sigma(z) - y)$$

• Thus, as we wanted, the gradient is proportional to  $\sigma(z)$  –

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$$\frac{\partial C}{\partial \theta_j} = -\left[\frac{y(1-\sigma(z))-(1-y)\sigma(z)}{\sigma(z)(1-\sigma(z))}\right]\sigma'(z)x_j$$

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=  $(\sigma(z) - y)x_j$   
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• Similarly, 
$$\frac{\partial C}{\partial \theta_0} = (\sigma(z) - y)$$

- **Thus**, as we wanted, the gradient is proportional to  $\sigma(z) y$
- The greater the error, the faster the learning rate

Madhavan Mukund